DUKE UNIVERSITY

Math 218

MATRICES AND VECTOR SPACES

Exam II

Name:

NetID:

Solutions

I have adhered to the Duke Community Standard in completing this exam. Signature:

October 22, 2021

- There are 100 points and 5 problems on this 50-minute exam.
- Unless otherwise stated, your answers must be supported by clear and coherent work to receive credit.
- The back of each page of this exam is left blank and may be used for scratch work.
- Scratch work will not be graded unless it is clearly labeled and requested in the body of the original problem.



Problem 1. Consider the matrix $A = \begin{bmatrix} 1 & 0 & -2 \\ -1 & -1 & 1 \\ 1 & 0 & -2 \end{bmatrix}$.

(6 pts) (a) Determine if $\begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} \in \operatorname{Null}(A)$.

Solution. This is a question of whether or not $A\begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} = \mathbf{O}$. The calculation

$$\begin{bmatrix} A \\ 1 & 0 & -2 \\ -1 & -1 & 1 \\ 1 & 0 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

then tells us that $\begin{bmatrix} 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} \notin \operatorname{Null}(A)$.

(6 pts) (b) Determine if $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}} \in \operatorname{Col}(A)$.

Solution. This is a question of whether or not $A\mathbf{x} = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$ is consistent, which we determine with a few row-reductions $\begin{bmatrix} 1 & 0 & -2 & | & 1 \end{bmatrix} \mathbf{r}_2 + \mathbf{r}_1 \rightarrow \mathbf{r}_2 \quad \begin{bmatrix} 1 & 0 & -2 & | & 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & 0 & -2 & 1 \\ -1 & -1 & 1 & 0 \\ 1 & 0 & -2 & 1 \end{bmatrix} \xrightarrow{r_2 + r_1 \to r_2} \begin{bmatrix} 1 & 0 & -2 & 1 \\ r_3 - r_1 \to r_3 \\ \hline 0 & -1 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The system is consistent, so $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}} \in \operatorname{Col}(A)$. Additionally, one might notice that $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$ is the first column of A minus the second column.

(6 pts) (c) Is $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}^{\mathsf{T}}$ an eigenvector of A? If so, what is the associated eigenvalue?

Solution. This is a question of whether or not $A\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}^{\mathsf{T}} = \lambda \cdot \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}^{\mathsf{T}}$ for some scalar λ . Here, we have

$$\begin{bmatrix} 1 & 0 & -2 \\ -1 & -1 & 1 \\ 1 & 0 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix} = -1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

We find that $\begin{bmatrix} 1 & 1 \end{bmatrix}^{\mathsf{T}}$ is an eigenvector of A and the associated eigenvalue is $\lambda = -1$.

(7 pts) **Problem 2.** Suppose that A is a matrix and v is a vector satisfying $v \in \mathcal{E}_A(-3)$. Show that v is an eigenvector of $M = A^2 - A$ and identify the corresponding eigenvalue.

Solution. We are given that $v \in \mathcal{E}_A(-3)$ which means $Av = -3 \cdot v$. It follows that

$$Mv = (A^{2} - A)v = A^{2}v - Av = (-3)^{2} \cdot v - (-3) \cdot v = (9+3) \cdot v = 12 \cdot v$$

This shows that $\boldsymbol{v} \in \mathcal{E}_M(12)$.

Problem 3. The first row of a matrix A is the vector $\begin{bmatrix} 1 & -1 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$ and the first column is the vector $\begin{bmatrix} 1 & 3 & -1 \end{bmatrix}^{\mathsf{T}}$. (7 pts) (a) If possible, determine if $\begin{bmatrix} 2 & 4 & 3 \end{bmatrix}^{\mathsf{T}} \in \operatorname{Null}(A^{\mathsf{T}})$. If this is not possible, then explain why.

Solution. Vectors in Null(A^{\intercal}) must be orthogonal to the column space Col(A). We are told that $\begin{bmatrix} 1 & 3 & -1 \end{bmatrix}^{\intercal}$ is the first column, so the inner product

$$\langle \begin{bmatrix} 2 & 4 & 3 \end{bmatrix}^{\mathsf{T}}, \begin{bmatrix} 1 & 3 & -1 \end{bmatrix}^{\mathsf{T}} \rangle = 11 \neq 0$$

tells us that $\begin{bmatrix} 2 & 4 & 3 \end{bmatrix}^{\mathsf{T}} \notin \operatorname{Null}(A^{\mathsf{T}}).$

(10 pts) (b) Now, suppose that $\text{Null}(A) = \text{Span}\{v_1, v_2, v_3\}$ where $\{v_1, v_2, v_3\}$ is linearly independent. Fill in every missing label in the picture of the four fundamental subspaces below, including the dimension of each fundamental subspace.



The fact that $\begin{bmatrix} 1 & -1 & 0 & 1 \end{bmatrix}^{\mathsf{T}}$ is the first row and $\begin{bmatrix} 1 & 3 & -1 \end{bmatrix}^{\mathsf{T}}$ is the first column means that A looks like

$$A = \begin{bmatrix} 1 & -1 & 0 & 1 \\ 3 & * & * & * \\ -1 & * & * & * \end{bmatrix}$$

So, A is 3×4 , which means $\mathbb{R}^4 \xrightarrow{A} \mathbb{R}^3$. Furthermore, we are told that $\{v_1, v_2, v_3\}$ is a basis of Null(A), so dim Null(A) = 3. The rest of the dimensions follow from the rank-nullity theorem.

(8 pts) (c) Suppose again that $Null(A) = Span\{v_1, v_2, v_3\}$ where $\{v_1, v_2, v_3\}$ is linearly independent. Find A. Solution. The picture of the four fundamental subspaces tells us that $rank(A) = \dim Col(A) = 1$, which means every column of A is a multiple of the first column. Since we are given the first row of A, we have

$$A = \begin{bmatrix} 1 & -1 & 0 & 1 \\ 3 & -3 & 0 & 3 \\ -1 & 1 & 0 & -1 \end{bmatrix}$$

Problem 4. A matrix A has projection onto $Col(A^{\intercal})$ and projection onto Col(A) given by

$$P_{\text{Col}(A^{\intercal})} = \begin{bmatrix} 2/3 & -1/3 & -1/3 & 0\\ -1/3 & 1/3 & 0 & 1/3\\ -1/3 & 0 & 1/3 & -1/3\\ 0 & 1/3 & -1/3 & 2/3 \end{bmatrix} \qquad P_{\text{Col}(A)} = \begin{bmatrix} 5/9 & 4/9 & -2/9\\ 4/9 & 5/9 & 2/9\\ -2/9 & 2/9 & * \end{bmatrix}$$

Note that the (3,3) entry of $P_{\text{Col}(A)}$ is unknown.

(9 pts) (a) Is the system $A^{\mathsf{T}} \boldsymbol{x} = \begin{bmatrix} 3 & 3 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ consistent?

Solution. This is equivalent to asking if $\begin{bmatrix} 3 & 3 & 0 & 0 \end{bmatrix}^{\mathsf{T}} \in \operatorname{Col}(A^{\mathsf{T}})$, which we can verify using the projection matrix $P_{\text{Col}(A^{\intercal})}$. Here, the relevant calculation is

$$\begin{bmatrix} 2/3 & -1/3 & -1/3 & 0\\ -1/3 & 1/3 & 0 & 1/3\\ -1/3 & 0 & 1/3 & -1/3\\ 0 & 1/3 & -1/3 & 2/3 \end{bmatrix} \begin{bmatrix} 3\\ 3\\ 0\\ 0\\ 0 \end{bmatrix} = \begin{bmatrix} 1\\ 0\\ -1\\ 1 \end{bmatrix} \neq \begin{bmatrix} 3\\ 3\\ 0\\ 0 \end{bmatrix}$$

Projecting $\begin{bmatrix} 3 & 3 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ onto $\operatorname{Col}(A^{\mathsf{T}})$ changes $\begin{bmatrix} 3 & 3 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$, so $\begin{bmatrix} 3 & 3 & 0 & 0 \end{bmatrix}^{\mathsf{T}} \notin \operatorname{Col}(A^{\mathsf{T}})$.

(9 pts) (b) Find the projection of $\begin{bmatrix} 9 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ onto $\operatorname{Null}(A^{\mathsf{T}})$.

Solution. The projection of $\begin{bmatrix} 9 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ onto $\operatorname{Col}(A)$ is

$$\begin{bmatrix} P_{\text{Col}(A)} \\ 5/9 & 4/9 & -2/9 \\ 4/9 & 5/9 & 2/9 \\ -2/9 & 2/9 & * \end{bmatrix} \begin{bmatrix} 9 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 4 \\ -2 \end{bmatrix}$$

Our orthogonality conditions then tell us that the projection of $\begin{bmatrix} 9 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ onto $\operatorname{Null}(A^{\mathsf{T}})$ is

$$\begin{bmatrix} 9 & 0 & 0 \end{bmatrix}^{\mathsf{T}} - \begin{bmatrix} 5 & 4 & -2 \end{bmatrix}^{\mathsf{T}} = \begin{bmatrix} 4 & -4 & 2 \end{bmatrix}^{\mathsf{T}}$$

(7 pts) (c) Find the missing (3,3) entry of $P_{\text{Col}(A)}$. Hint. Start by explaining the relationship between the dimensions of $\operatorname{Col}(A^{\intercal})$ and $\operatorname{Col}(A)$. What property of projection matrices relates to dimension?

Solution. We know the general formula trace $(P_V) = \dim(V)$. Since $\dim \operatorname{Col}(A^{\intercal}) = \dim \operatorname{Col}(A) = \operatorname{rank}(A)$, our two given projection matrices must have the same trace, which gives

$$\frac{2+1+1+2}{3} = \frac{5+5+9*}{9}$$

This reduces to 2 = (10 + 9*)/9 which gives * = 8/9.

Problem 5. The following QR-factorization was calculated using the Gram-Schmidt algorithm.

$$\begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 5 \\ 1 & 2 & -1 \\ 0 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & * & 1/2 \\ 1/\sqrt{2} & * & 1/2 \\ 1/\sqrt{2} & * & -1/2 \\ 0 & * & 1/2 \end{bmatrix} \begin{bmatrix} \sqrt{2} & \sqrt{2} & 2\sqrt{2} \\ 0 & 2 & -4 \\ 0 & 0 & 2 \end{bmatrix}$$

Note that the second column of Q is missing.

(9 pts) (a) rank $(A) = \underline{3}$, rank $(Q) = \underline{3}$, and rank $(R) = \underline{3}$

(8 pts) (b) Use the Gram-Schmidt algorithm to find the missing column of Q. You must use the Gram-Schmidt algorithm to receive any credit.

Solution. We apply Gram-Schmidt to the columns of A. This gives

$$\begin{split} \boldsymbol{w}_{1} &= \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} \\ \boldsymbol{w}_{2} &= \begin{bmatrix} 1 & 0 & 2 & 1 \end{bmatrix}^{\mathsf{T}} - \operatorname{proj}_{\boldsymbol{w}_{1}}(\begin{bmatrix} 1 & 0 & 2 & 1 \end{bmatrix}^{\mathsf{T}}) \\ &= \begin{bmatrix} 1 & 0 & 2 & 1 \end{bmatrix}^{\mathsf{T}} - \frac{\langle \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}}, \begin{bmatrix} 1 & 0 & 2 & 1 \end{bmatrix}^{\mathsf{T}} \rangle}{\langle \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}}, \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} \rangle} \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} \\ &= \begin{bmatrix} 1 & 0 & 2 & 1 \end{bmatrix}^{\mathsf{T}} - \frac{2}{2} \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}^{\mathsf{T}} \\ &= \begin{bmatrix} 1 & -1 & 1 & 1 \end{bmatrix}^{\mathsf{T}} \end{split}$$

Normalizing \boldsymbol{w}_2 gives our missing column of Q as $\boldsymbol{q}_2 = \begin{bmatrix} 1/2 & -1/2 & 1/2 \end{bmatrix}^{\mathsf{T}}$.

(8 pts) (c) The vector $\boldsymbol{b} = \begin{bmatrix} 2 & 2 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ is orthogonal to the second column of Q. Find the least-squares approximate solution to $A\boldsymbol{x} = \boldsymbol{b}$.

Solution. The least squares system $A^{\mathsf{T}}A\hat{x} = A^{\mathsf{T}}b$ reduces to $R\hat{x} = Q^{\mathsf{T}}b$. We are told that the missing column of Q is orthogonal to b, so we can calculate

$$\begin{bmatrix} 0 & \frac{\sqrt{2}}{\sqrt{2}} & \frac{\sqrt{2}}{\sqrt{2}} & 0\\ * & * & * & *\\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \mathbf{b} \\ 2\\ 2\\ 0\\ 0 \end{bmatrix} = \begin{bmatrix} \sqrt{2} \\ 0\\ 2 \end{bmatrix}$$

The system $R\hat{x} = Q^{\intercal}b$ is then solved with back-substitution.

This gives $\widehat{x} = \begin{bmatrix} -3 & 2 & 1 \end{bmatrix}^{\mathsf{T}}$.