DUKE UNIVERSITY

Матн 218D-2

MATRICES AND VECTORS

Exam I

Name:

NetID:

Solutions

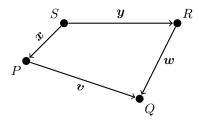
I have adhered to the Duke Community Standard in completing this exam. Signature:

September 29, 2023

- There are 100 points and 6 problems on this 50-minute exam.
- Unless otherwise stated, your answers must be supported by clear and coherent work to receive credit.
- The back of each page of this exam is left blank and may be used for scratch work.
- Scratch work will not be graded unless it is clearly labeled and requested in the body of the original problem.



Problem 1. This figure depicts displacement vectors \boldsymbol{v} , \boldsymbol{w} , \boldsymbol{x} , and \boldsymbol{y} between points P, Q, R, and S in \mathbb{R}^5 (so each of P, Q, R, and S has five coordinates). Throughout this problem, assume that A is a matrix satisfying $A\boldsymbol{v} = \begin{bmatrix} 2\\ 3 \end{bmatrix}$ and $A\boldsymbol{w} = \begin{bmatrix} 7\\ 1 \end{bmatrix}$.



(3 pts) (a) Which point is the tail of $\pmb{v}? ~~ \surd ~ P ~~ \bigcirc ~ Q ~~ \bigcirc ~ R ~~ \bigcirc ~ S$

- (3 pts) (b) Only one of the following formulas for \boldsymbol{w} is correct. Select this formula. $\bigcirc \boldsymbol{w} = \overrightarrow{QR} \quad \bigcirc \boldsymbol{w} = -\overrightarrow{RQ} \quad \bigcirc \boldsymbol{w} = \overrightarrow{Q} \quad \checkmark \boldsymbol{w} = \overrightarrow{RQ} \quad \bigcirc \boldsymbol{w} = \overrightarrow{R}$
- (3 pts) (c) Only one of the following formulas for \overrightarrow{RP} is correct. Select this formula. $\bigcirc \overrightarrow{RP} = \mathbf{x} + \mathbf{y} \quad \sqrt{\overrightarrow{RP}} = \mathbf{x} - \mathbf{y} \quad \bigcirc \overrightarrow{RP} = -\mathbf{x} - \mathbf{y} \quad \bigcirc \overrightarrow{RP} = \mathbf{w} + \mathbf{v} \quad \bigcirc \overrightarrow{RP} = \mathbf{y}$
- (3 pts) (d) The number of rows of A is 2 and the number of columns of A is 5.
- (4 pts) (e) If we assumed that P and Q have coordinates P(1, 1, 1, 1, 1) and Q(1, 1, 2, 1, 1), then only one of the following statements is guaranteed to be correct. Select this statement.
 - The second column of A is $\begin{bmatrix} 2\\3 \end{bmatrix}$ The second column of A is $\begin{bmatrix} 7\\1 \end{bmatrix}$ The third column of A is $\begin{bmatrix} -2\\-3 \end{bmatrix}$ ○ The third column of A is $\begin{bmatrix} 7\\1 \end{bmatrix}$ \checkmark The third column of A is $\begin{bmatrix} 2\\3 \end{bmatrix}$
- (8 pts) (f) Calculate the matrix-vector product A(x y + w). Clearly explain your reasoning to receive credit. Solution. The diagram demonstrates that $x - y = \overrightarrow{RP} = w - v$, which implies

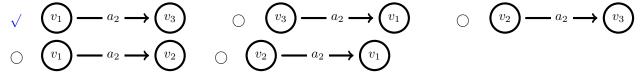
$$A(\boldsymbol{x} - \boldsymbol{y} + \boldsymbol{w}) = A(\boldsymbol{w} - \boldsymbol{v} + \boldsymbol{w}) = A(2 \cdot \boldsymbol{w} - \boldsymbol{v}) = 2 \cdot A\boldsymbol{w} - A\boldsymbol{v} = 2 \cdot \begin{bmatrix} 7\\1 \end{bmatrix} - \begin{bmatrix} 2\\3 \end{bmatrix} = \begin{bmatrix} 12\\-1 \end{bmatrix}$$

Problem 2. The equation below depicts the result of multiplying the incidence matrix A of a digraph G by another matrix B.

$$A \qquad \begin{bmatrix} 1 & 1 & 1 & 0 & 7 & 3 \\ 3 & 0 & 1 & 1 & 5 & 9 \\ 0 & 0 & 1 & 0 & 7 & 0 \\ 2 & 1 & 1 & 0 & 7 & 6 \\ 0 & 0 & 1 & 0 & 7 & 0 \end{bmatrix} = \begin{bmatrix} -2 & 0 & -1 & -1 & -5 & * \\ 0 & 0 & 0 & 0 & 0 & * \\ 3 & 0 & 1 & 1 & 5 & * \\ 0 & 0 & 1 & 0 & 7 & * \\ -1 & 0 & -1 & 0 & -7 & * \end{bmatrix}$$

Note that the entries in the last column of AB are unknown and marked as *.

- (6 pts) (a) The number of nodes in G is <u>5</u>, the number of arrows in G is <u>5</u>, and $\chi(G) = 0$.
- (5 pts) (b) Which of the following is the correct visualization of the second arrow a_2 in the digraph G?



- (4 pts) (c) Suppose we make G a weighted digraph by assigning a weight of 5 to the second arrow a_2 and a weight of 7 to all of the other arrows. Then the net flow through the last node of G is -7.
- (4 pts) (d) What is the missing column of AB?

$$\bigcirc \begin{bmatrix} -2\\0\\3\\0\\-1 \end{bmatrix} \bigcirc \begin{bmatrix} 3\\9\\0\\6\\0 \end{bmatrix} \checkmark \checkmark \begin{bmatrix} -6\\0\\9\\0\\-3 \end{bmatrix} \bigcirc \begin{bmatrix} 1\\3\\0\\2\\0 \end{bmatrix} \bigcirc \text{ not enough information to tell}$$

(5 pts) (e) Which of these statements best articulates the relationship of A to the terms "singular" and "nonsingular"? \sqrt{A} is singular. $\bigcirc A$ is nonsingular. $\bigcirc A$ is neither singular nor nonsingular.

 \bigcirc A is either singular or nonsingular, but we do not have enough information to decide which.

(12 pts) **Problem 3.** Select every matrix below whose rank is two (each option is worth 2pts).

(12 pts) **Problem 4.** An $n \times n$ matrix M is called *idempotent* if $M^2 = M$.

Suppose that $A = XMX^{-1}$ where M is idempotent. Show that A is idempotent. You must avoid circular logic to receive credit.

Solution. We are given $A = XMX^{-1}$ where M is idempotent, which means that $M^2 = M$. We wish to demonstrate that A is idempotent, which means we want $A^2 = A$. This is then accomplished with

 $A^{2} = (XMX^{-1})(XMX^{-1}) = XMX^{-1}XMX^{-1} = XMI_{n}MX^{-1} = XMMX^{-1} = XMX^{-1} = A$

Problem 5. The data below depicts the result of representing the Gauß-Jordan algorithm applied to a matrix A with elementary matrices.

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -7 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 6 & 9 & 0 & 0 \\ 0 & -5 & -10 & -25 & 0 & -35 \\ 0 & 1 & 2 & 5 & 1 & 7 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 6 & 9 & 0 & 0 \\ 0 & 1 & 2 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Note that the elementary matrix E_1 is not explicitly described.

- (4 pts) (a) The second elementary row operation used in the algorithm was $\underline{r_3 r_2 \rightarrow r_3}$. You must use the proper notation we learned in class to represent this elementary row operation.
- (8 pts) (b) Find E_1 . Clearly explain your reasoning to receive credit.

Solution. This is the elementary matrix corresponding to the first elementary row operation in the Gauß-Jordan algorithm when applied to A, which is $-\frac{1}{5} \cdot \mathbf{r}_2 \rightarrow \mathbf{r}_2$. The elementary matrix we are looking for is obtained by applying this operation to the identity matrix, which gives

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-1/5 \cdot \boldsymbol{r}_2 \to \boldsymbol{r}_2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1/5 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Problem 6. The data below depicts a PA = LU factorization along with the inverse marix L^{-1} and a vector **b**.

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} & & A & \\ & & \\ \end{bmatrix} = \begin{bmatrix} & & L & \\ & & \\ \end{bmatrix} \begin{bmatrix} 1 & 3 & 9 & 19 & 4 \\ 0 & 0 & 5 & 10 & 6 \\ 0 & 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad L^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 3 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 \\ 1 & 2 & 1 & 3 \end{bmatrix} \quad \boldsymbol{b} = \begin{bmatrix} 0 \\ h-1 \\ 0 \\ h+1 \end{bmatrix}$$

Note that A and L are not explicitly described, and that \boldsymbol{b} is defined in terms of a constant h.

(4 pts) (a) nullity $(U^{\intercal}) = \underline{1}$

(12 pts) (b) There is only one value of h that makes the system Ax = b consistent. Find this value of h. Clearly explain your reasoning to receive credit.

Solution. In class we demonstrated that the solutions to $A\mathbf{x} = \mathbf{b}$ are the solutions to $U\mathbf{x} = \mathbf{y}$ where $L\mathbf{y} = P\mathbf{b}$. Conveniently, we are given L^{-1} , so we can quickly solve $L\mathbf{y} = P\mathbf{b}$ with

$$\boldsymbol{y} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 3 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 \\ 1 & 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} b \\ 0 \\ h-1 \\ 0 \\ h+1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 3 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 \\ 1 & 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} h+1 \\ 0 \\ 0 \\ h-1 \end{bmatrix} = \begin{bmatrix} h+1 \\ 3h+3 \\ 3h+3 \\ 4h-2 \end{bmatrix}$$

Now, in augmented form, the system $U\boldsymbol{x} = \boldsymbol{y}$ is

$$\begin{bmatrix} 1 & 3 & 9 & 19 & 4 & h+1 \\ 0 & 0 & 5 & 10 & 6 & 3h+3 \\ 0 & 0 & 0 & 0 & 4 & 3h+3 \\ 0 & 0 & 0 & 0 & 0 & 4h-2 \end{bmatrix}$$

The only way to avoid a pivot in the augmented column is to force 4h - 2 = 0, which only works when h = 1/2.