

# DUKE UNIVERSITY

MATH 218D-2

MATRICES AND VECTORS

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## Exam I

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*Name:*

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*I have adhered to the Duke Community Standard in completing this exam.*

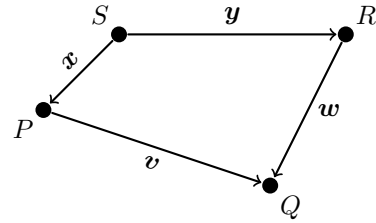
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September 29, 2023

- There are 100 points and 6 problems on this 50-minute exam.
- Unless otherwise stated, your answers must be supported by clear and coherent work to receive credit.
- The back of each page of this exam is left blank and may be used for scratch work.
- Scratch work will not be graded unless it is clearly labeled and requested in the body of the original problem.

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**Problem 1.** This figure depicts displacement vectors  $\mathbf{v}$ ,  $\mathbf{w}$ ,  $\mathbf{x}$ , and  $\mathbf{y}$  between points  $P$ ,  $Q$ ,  $R$ , and  $S$  in  $\mathbb{R}^5$  (so each of  $P$ ,  $Q$ ,  $R$ , and  $S$  has five coordinates). Throughout this problem, assume that  $A$  is a matrix satisfying  $A\mathbf{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$  and  $A\mathbf{w} = \begin{bmatrix} 7 \\ 1 \end{bmatrix}$ .



(3 pts) (a) Which point is the *tail* of  $\mathbf{v}$ ?   $P$    $Q$    $R$    $S$

(3 pts) (b) Only one of the following formulas for  $\mathbf{w}$  is correct. Select this formula.

$\mathbf{w} = \overrightarrow{QR}$    $\mathbf{w} = -\overrightarrow{RQ}$    $\mathbf{w} = \overrightarrow{Q}$    $\mathbf{w} = \overrightarrow{RQ}$    $\mathbf{w} = \overrightarrow{R}$

(3 pts) (c) Only one of the following formulas for  $\overrightarrow{RP}$  is correct. Select this formula.

$\overrightarrow{RP} = \mathbf{x} + \mathbf{y}$    $\overrightarrow{RP} = \mathbf{x} - \mathbf{y}$    $\overrightarrow{RP} = -\mathbf{x} - \mathbf{y}$    $\overrightarrow{RP} = \mathbf{w} + \mathbf{v}$    $\overrightarrow{RP} = \mathbf{y}$

(3 pts) (d) The number of rows of  $A$  is \_\_\_\_\_ and the number of columns of  $A$  is \_\_\_\_\_.

(4 pts) (e) If we assumed that  $P$  and  $Q$  have coordinates  $P(1, 1, 1, 1, 1)$  and  $Q(1, 1, 2, 1, 1)$ , then only one of the following statements is guaranteed to be correct. Select this statement.

The second column of  $A$  is  $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$   The second column of  $A$  is  $\begin{bmatrix} 7 \\ 1 \end{bmatrix}$   The third column of  $A$  is  $\begin{bmatrix} -2 \\ -3 \end{bmatrix}$   
 The third column of  $A$  is  $\begin{bmatrix} 7 \\ 1 \end{bmatrix}$   The third column of  $A$  is  $\begin{bmatrix} 2 \\ 3 \end{bmatrix}$

(8 pts) (f) Calculate the matrix-vector product  $A(\mathbf{x} - \mathbf{y} + \mathbf{w})$ . Clearly explain your reasoning to receive credit.



(12 pts) **Problem 4.** An  $n \times n$  matrix  $M$  is called *idempotent* if  $M^2 = M$ .

Suppose that  $A = XMX^{-1}$  where  $M$  is idempotent. Show that  $A$  is idempotent. **You must avoid circular logic to receive credit.**

**Problem 5.** The data below depicts the result of representing the Gauß-Jordan algorithm applied to a matrix  $A$  with elementary matrices.

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -7 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} E_1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 6 & 9 & 0 & 0 \\ 0 & -5 & -10 & -25 & 0 & -35 \\ 0 & 1 & 2 & 5 & 1 & 7 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 6 & 9 & 0 & 0 \\ 0 & 1 & 2 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Note that the elementary matrix  $E_1$  is not explicitly described.

(4 pts) (a) The *second* elementary row operation used in the algorithm was \_\_\_\_\_. **You must use the proper notation we learned in class to represent this elementary row operation.**

(8 pts) (b) Find  $E_1$ . Clearly explain your reasoning to receive credit.

**Problem 6.** The data below depicts a  $PA = LU$  factorization along with the inverse matrix  $L^{-1}$  and a vector  $\mathbf{b}$ .

$$\begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{matrix} P \\ \\ \\ \end{matrix} \begin{bmatrix} A \\ \\ \\ \end{bmatrix} = \begin{bmatrix} L \\ \\ \\ \end{bmatrix} \begin{bmatrix} 1 & 3 & 9 & 19 & 4 \\ 0 & 0 & 5 & 10 & 6 \\ 0 & 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} U \\ \\ \\ \end{matrix} \quad L^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 3 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 \\ 1 & 2 & 1 & 3 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} 0 \\ h-1 \\ 0 \\ h+1 \end{bmatrix}$$

Note that  $A$  and  $L$  are not explicitly described, and that  $\mathbf{b}$  is defined in terms of a constant  $h$ .

(4 pts) (a)  $\text{nullity}(U^\top) = \underline{\hspace{2cm}}$

(12 pts) (b) There is only one value of  $h$  that makes the system  $A\mathbf{x} = \mathbf{b}$  consistent. Find this value of  $h$ . Clearly explain your reasoning to receive credit.