DUKE UNIVERSITY

Матн 218D-2

MATRICES AND VECTORS

Exam II

Name:

Unique ID:

Solutions

I have adhered to the Duke Community Standard in completing this exam. Signature:

October 25, 2024

- There are 100 points and 4 problems on this 50-minute exam.
- Unless otherwise stated, your answers must be supported by clear and coherent work to receive credit.
- The back of each page of this exam is left blank and may be used for scratch work.
- Scratch work will not be graded unless it is clearly labeled and requested in the body of the original problem.



Problem 1. Suppose that $A\mathbf{x} = \mathbf{b}$ is a *consistent system* where A is 31×17 and that \mathbf{y} and \mathbf{z} are solutions to this system where $\mathbf{y} \neq \mathbf{z}$ (this means that \mathbf{y} and \mathbf{z} are vectors satisfying $A\mathbf{y} = \mathbf{b}$ and $A\mathbf{z} = \mathbf{b}$).

- (3 pts) (a) The vector \boldsymbol{b} has <u>17</u> coordinates and the vectors \boldsymbol{y} and \boldsymbol{z} have <u>31</u> coordinates.
- (4 pts) (b) Only one of the following statements is guaranteed to be correct. Select this statement.
 - $\bigcirc \mathbf{b}$ belongs to the row space of $A \bigcirc \mathbf{b}$ belongs to the null space of A
 - \sqrt{b} belongs to the column space of $A \cap b$ belongs to the left null space of A
 - \bigcirc we do not have enough information to determine if **b** belongs to one of the four fundamental subspaces of A
- (4 pts) (c) Only one of the following statements is guaranteed to accurately characterize $A^{\intercal}Ay$. Select this statement.

 $\sqrt{A^{\mathsf{T}}Ay}$ is a vector in the row space of $A \cap A^{\mathsf{T}}Ay$ is a vector in the null space of A

- $\bigcirc A^{\intercal}Ay$ is a vector in the column space of $A \bigcirc A^{\intercal}Ay$ is a vector in the left null space of A
- (8 pts) (d) Prove that $y z \in \text{Null}(A^{\intercal}A)$. Use the space outside the box below to brainstorm your thoughts, but your proof must be neatly and succinctly presented in the box below. You must avoid circular reasoning to receive credit.

Solution. We know that $A\mathbf{y} = \mathbf{b}$ and that $A\mathbf{z} = \mathbf{b}$. We wish to prove that $\mathbf{y} - \mathbf{z} \in \text{Null}(A^{\intercal}A)$, which is the same as demonstrating that $A^{\intercal}A(\mathbf{y} - \mathbf{z}) = \mathbf{0}$. The proof then succinctly fits into our box below:

- $A^{\mathsf{T}}A(\boldsymbol{y}-\boldsymbol{z}) = A^{\mathsf{T}}A\boldsymbol{y} A^{\mathsf{T}}A\boldsymbol{z} = A^{\mathsf{T}}\boldsymbol{b} A^{\mathsf{T}}\boldsymbol{b} = \boldsymbol{O}$
- (9 pts) (e) The facts that $y \neq z$ and that $y z \in \text{Null}(A^{\intercal}A)$ imply that some, but not all, of the following statements are *guaranteed* to be true. Select the true statements (1.5pts each).

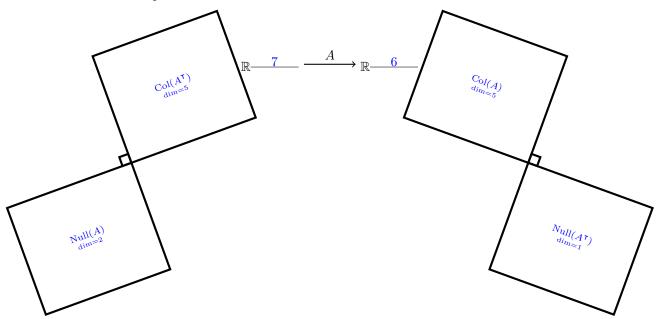
 $\sqrt{\dim \operatorname{Null}(A^{\intercal}A)} > 0$ $\bigcirc \dim \operatorname{Null}(A^{\intercal}A) = 1$ $\bigcirc A^{\intercal}A$ has independent columns

 $\sqrt{A^{\intercal}A}$ is singular $\bigcirc \lambda = 0$ is not and eigenvalue of $A = \sqrt{y - z}$ is an eigenvector of $A^{\intercal}A$

Solution. The fact that $\mathbf{y} \neq \mathbf{z}$ means that $\mathbf{y} - \mathbf{z} \neq \mathbf{O}$. The fact that $\mathbf{y} - \mathbf{z} \in \text{Null}(A^{\intercal}A)$ then tells us that Null $(A^{\intercal}A)$ contains a vector other than the zero vector. From this we conclude that dim Null $(A^{\intercal}A) > 0$ but we don't have enough information to say that dim Null $(A^{\intercal}A) = 1$. Since nullity $(A^{\intercal}A) = \dim \text{Null}(A^{\intercal}A) > 0$, we further conclude that $A^{\intercal}A$ has dependent columns and is therefore singular (so $\lambda = 0$ is and eigenvalue of $A^{\intercal}A$). Since $A^{\intercal}A(\mathbf{y}-\mathbf{z}) = \mathbf{O} = 0 \cdot (\mathbf{y}-\mathbf{z})$, we know that $\mathbf{y} - \mathbf{z}$ is an eigenvector of $A^{\intercal}A$ (with eigenvalue zero).

$$\mathbf{Problem \ 2. \ Suppose \ A \ satisfies \ rref(A) = \begin{bmatrix} 1 & 0 & 0 & 0 & -5 & 3 & 0 \\ 0 & 1 & 0 & 0 & 4 & 4 & 0 \\ 0 & 0 & 1 & 0 & -3 & 2 & 0 \\ 0 & 0 & 0 & 1 & -1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \text{ and } \operatorname{rref}(A^{\intercal}) = \begin{bmatrix} 1 & 4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

(10 pts) (a) Fill in every missing label in the picture of the four fundamental subspaces of A below, including the dimension of each fundamental subspace.



(3 pts) (b) Which of the following is the most accurate geometric description of the *left null space* of A? () a plane in \mathbb{R}^6 () a point with six coordinates () a line in \mathbb{R}^7 \checkmark a line in \mathbb{R}^6 () a plane in \mathbb{R}^7

- (4 pts) (c) Only one of the following statements accurately describes the columns of A. Select this statement.
 - \bigcirc A has independent columns \bigcirc every choice of five columns of A will be independent

 \checkmark it is impossible to find six independent vectors among the columns of A

- \bigcirc the first four columns of A form a basis of $\operatorname{Col}(A)$
- (4 pts) (d) The projection matrix P onto the row space of A is $P = X(X^{\mathsf{T}}X)^{-1}X^{\mathsf{T}}$ where X is $\xrightarrow{7}{5}$
- (10 pts) (e) Let V be the vector space spanned by the rows of $\operatorname{rref}(A^{\intercal})$. Find a basis of V^{\perp} . Clearly explain your work to receive credit.

Solution. From class we know that the nonzero rows of $\operatorname{rref}(A^{\intercal})$ form a basis of $\operatorname{Col}(A)$. Including the rows of zeros doesn't change the span, so $V = \operatorname{Col}(A)$, which means we want to find a basis of $V^{\perp} = \operatorname{Null}(A^{\intercal})$. The picture tells us that dim $\operatorname{Null}(A^{\intercal}) = 1$, so we need only find one nonzero solution to $A^{\intercal} \boldsymbol{x} = \boldsymbol{O}$. The given $\operatorname{rref}(A^{\intercal})$ tells us that the equations defining $A^{\intercal} \boldsymbol{x} = \boldsymbol{O}$ are

$$x_1 + 4x_2 = 0 \qquad \qquad x_3 = 0 \qquad \qquad x_4 = 0 \qquad \qquad x_5 = 0 \qquad \qquad x_6 = 0$$

The free variable is $x_2 = c_1$ so the general solution is

$$\begin{bmatrix} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \end{bmatrix}^{\mathsf{T}} = \begin{bmatrix} -4c_1 & c_1 & 0 & 0 & 0 \end{bmatrix}^{\mathsf{T}} = c_1 \cdot \begin{bmatrix} -4 & 1 & 0 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$$

This tells us that any nonzero multiple of $\begin{bmatrix} -4 & 1 & 0 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$ is a valid basis of V^{\perp} .

Problem 3. One of the eigenvalues of $A = \begin{bmatrix} 5 & -5 & 0 & -5 \\ 25 & 0 & 25 & -5 \\ -5 & 5 & 0 & 5 \\ -25 & 0 & -25 & 5 \end{bmatrix}$ is $\lambda = 5$.

(10 pts) (a) Find a basis of $\mathcal{E}_A(5)$. Clearly explain your work to receive credit.

Solution. By definition, we want a basis of is

$$\mathcal{E}_{A}(5) = \operatorname{Null} \begin{bmatrix} 5 \cdot I_{4} - A & & \\ 0 & 5 & 0 & 5 \\ -25 & 5 & -25 & 5 \\ 5 & -5 & 5 & -5 \\ 25 & 0 & 25 & 0 \end{bmatrix} = \operatorname{Null} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \operatorname{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix} \right\}$$

The calculation of $\operatorname{rref}(5 \cdot I_4 - A)$ is done where without row-reductions by observing the column relations $\operatorname{Col}_3 = \operatorname{Col}_1$ and $\operatorname{Col}_4 = \operatorname{Col}_2$.

(9 pts) (b) Let P be the projection matrix onto $\mathcal{E}_A(5)$ and suppose that $v \in \mathcal{E}_A(5)$. Some, but not all, of the following statements are correct. Select each correct statement (1.5pts each).

 $\sqrt{A\boldsymbol{v}} = 5 \cdot \boldsymbol{v} \quad \bigcirc P\boldsymbol{v} = 5 \cdot \boldsymbol{v} \quad \bigcirc A\boldsymbol{v} = \boldsymbol{O} \quad \sqrt{P\boldsymbol{v}} = \boldsymbol{v} \quad \sqrt{\operatorname{trace}(P)} = \operatorname{gm}_A(5) \quad \bigcirc \operatorname{trace}(P) = 5$

(10 pts) (c) Let $\boldsymbol{b} = \begin{bmatrix} 4 & 0 & 6 & 2 \end{bmatrix}^{\mathsf{T}}$. If we assemble the basis vectors found for $\mathcal{E}_A(5)$ in part (a) of this problem into the columns of a matrix B, then we would find that $B(B^{\mathsf{T}}B)^{-1}B^{\mathsf{T}}\boldsymbol{b} = \begin{bmatrix} -1 & -1 & 1 & 1 \end{bmatrix}^{\mathsf{T}}$. Use this information to calculate the error in the least squares problem associated to the system $B\boldsymbol{x} = \boldsymbol{b}$ and fill in the blank: $E = \begin{bmatrix} 52 \end{bmatrix}$. Clearly explain your work to receive credit.

Solution. The error in the least squares problem assiciated to $B\boldsymbol{x} = \boldsymbol{b}$ is the square length of the difference between \boldsymbol{b} and the projection of \boldsymbol{b} to $\operatorname{Col}(\boldsymbol{b})$. We are given $\boldsymbol{b} = \begin{bmatrix} 4 & 0 & 6 & 2 \end{bmatrix}^{\mathsf{T}}$ and the projection of \boldsymbol{b} to $\operatorname{Col}(B)$ is $\begin{bmatrix} -1 & -1 & 1 & 1 \end{bmatrix}^{\mathsf{T}}$, so our error is

$$E = \left\| \begin{bmatrix} 4\\0\\6\\2 \end{bmatrix} - \begin{bmatrix} -1\\-1\\1\\1\\1 \end{bmatrix} \right\|^2 = \left\| \begin{bmatrix} 5\\1\\5\\1 \end{bmatrix} \right\|^2 = 52$$

(12 pts) **Problem 4.** Find the value of y_0 so that the least squares line of best fit to the data set

$$\{(-3, y_0), (-2, -1), (-4, 1)\}$$

is $\widehat{f}(t) = -2 - t$. Clearly explain your reasoning to receive credit.

Solution. A "perfect" line $f(t) = a_0 + a_1 t$ would satisfy

This is the system $A\boldsymbol{x} = \boldsymbol{b}$ where

$$A = \begin{bmatrix} 1 & -3 \\ 1 & -2 \\ 1 & -4 \end{bmatrix} \qquad \qquad \mathbf{x} = \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} \qquad \qquad \mathbf{b} = \begin{bmatrix} y_0 \\ -1 \\ 1 \end{bmatrix}$$

The associated least squares problem is $A^{\intercal}A\hat{x} = A^{\intercal}b$. The relevant data here is

$$\begin{bmatrix} A^{\mathsf{T}} & 1 \\ -3 & -2 & -4 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ 1 & -2 \\ 1 & -4 \end{bmatrix} = \begin{bmatrix} 3 & -9 \\ -9 & 29 \end{bmatrix} \qquad \hat{x} = \begin{bmatrix} \hat{a}_0 \\ \hat{a}_1 \end{bmatrix} \qquad \begin{bmatrix} A^{\mathsf{T}} & 1 \\ 1 & 1 & 1 \\ -3 & -2 & -4 \end{bmatrix} \begin{bmatrix} b \\ y_0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} y_0 \\ -3 y_0 - 2 \end{bmatrix}$$

The key to this problem is that we are told that the least squares line of best fit is $\hat{f}(t) = -t - 2 = \hat{a}_0 + \hat{a}_1 t$, which means that $\hat{a}_0 = -2$ and $\hat{a}_1 = -1$. The quantity $A^{\intercal}A\hat{x}$ is now

$$\begin{bmatrix} A^{\dagger}A & \hat{x} \\ 3 & -9 \\ -9 & 29 \end{bmatrix} \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ -11 \end{bmatrix}$$

Now, setting the vector $A^{\intercal}A\hat{x}$ equal to $A^{\intercal}b$ gives the equations

$$3 = y_0 \qquad -11 = -3 y_0 - 2$$

The value $y_0 = 3$ works in both equations. This is our $y_0!$