

DUKE UNIVERSITY

MATH 218D-2

MATRICES AND VECTORS

Exam I

Name:

Unique ID:

I have adhered to the Duke Community Standard in completing this exam.

Signature: _____

February 7, 2025

- There are 100 points and 5 problems on this 50-minute exam.
- Unless otherwise stated, your answers must be supported by clear and coherent work to receive credit.
- The back of each page of this exam is left blank and may be used for scratch work.
- Scratch work will not be graded unless it is clearly labeled and requested in the body of the original problem.

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Problem 1. The equation below depicts the result of multiplying two matrices A and B .

$$\begin{array}{c} \begin{matrix} \text{---} & \mathbf{r}_1^\top & \text{---} \\ \text{---} & \mathbf{v}^\top & \text{---} \\ \text{---} & \mathbf{r}_3^\top & \text{---} \\ \text{---} & \mathbf{r}_4^\top & \text{---} \\ \text{---} & \mathbf{r}_5^\top & \text{---} \end{matrix} \\ \left[\begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} \right] \end{array} \begin{array}{c} \begin{matrix} \text{---} & \mathbf{b}_1 & \text{---} \\ \text{---} & \mathbf{b}_2 & \text{---} \\ \text{---} & \mathbf{v} & \text{---} \\ \text{---} & \mathbf{b}_4 & \text{---} \end{matrix} \\ \left[\begin{array}{c} | \\ | \\ | \\ | \end{array} \right] \end{array} = \begin{bmatrix} -5 & 16 & -4 & 6 \\ 3 & -3 & 7 & -1 \\ -9 & 9 & -7 & 0 \\ -1 & -3 & 10 & 4 \\ 6 & 0 & 1 & 5 \end{bmatrix}$$

Note that the rows of A are labeled as $\mathbf{r}_1, \mathbf{v}, \mathbf{r}_3, \mathbf{r}_4, \mathbf{r}_5$ and that the columns of B are marked as $\mathbf{b}_1, \mathbf{b}_2, \mathbf{v}, \mathbf{b}_4$. In particular, note that the second row of A is equal to the third column of B and this vector is labeled as \mathbf{v} .

(6 pts) (a) $\langle \mathbf{r}_1, \mathbf{b}_1 \rangle = \underline{\hspace{2cm}}$, $\langle \mathbf{r}_4, \mathbf{b}_2 \rangle = \underline{\hspace{2cm}}$, and $\mathbf{r}_3^\top \mathbf{b}_4 = \underline{\hspace{2cm}}$

(2 pts) (b) Which, if any, of the following vectors is *orthogonal* to \mathbf{r}_5 ? Select all that apply (no partial credit).

- \mathbf{b}_1 \mathbf{b}_2 \mathbf{v} \mathbf{b}_4 none of these

(2 pts) (c) Which, if any, of the following vectors forms an *obtuse* angle with \mathbf{r}_5 ? Select all that apply (no partial credit).

- \mathbf{b}_1 \mathbf{b}_2 \mathbf{v} \mathbf{b}_4 none of these

(4 pts) (d) Let θ be the angle between \mathbf{v} and \mathbf{b}_4 . Then $\|\mathbf{v}\| \cdot \|\mathbf{b}_4\| \cdot \cos(\theta) = \underline{\hspace{2cm}}$.

(6 pts) (e) $\|\mathbf{v}\| = \underline{\hspace{2cm}}$ and the (3,3) entry of $B^\top B$ is $\underline{\hspace{2cm}}$

(3 pts) (f) Calculate this matrix product: $\begin{bmatrix} \text{---} & \mathbf{r}_5^\top & \text{---} \\ \text{---} & \mathbf{r}_3^\top & \text{---} \end{bmatrix} \begin{bmatrix} | & | \\ | & | \\ | & | \end{bmatrix} = \begin{bmatrix} & \\ & \end{bmatrix}$

(6 pts) (g) Calculate the matrix-vector product $A(\mathbf{b}_1 + \mathbf{b}_4)$. Clearly explain your reasoning to receive credit. Fill in the blank vector at the bottom of this page to make your answer clear.

$$A(\mathbf{b}_1 + \mathbf{b}_4) = \begin{bmatrix} \\ \\ \\ \\ \end{bmatrix}$$

The next problem references the concept of a *skew-symmetric matrix*, which is any matrix A satisfying $A^T = -A$.

Problem 2. Let \mathbf{v} and \mathbf{w} be two vectors in \mathbb{R}^n , both viewed as $n \times 1$ matrices. Let K be the matrix defined by the formula $K = \mathbf{v}\mathbf{w}^T - \mathbf{w}\mathbf{v}^T$.

(10 pts) (a) Show that K is skew-symmetric. Your solution should consist of a single string of equalities that is clear and coherent and avoids circular reasoning.

(10 pts) (b) Now, assume that $\|\mathbf{v}\| = 3$, $\|\mathbf{w}\| = 5$, and that \mathbf{v} and \mathbf{w} are orthogonal. Calculate $\|K\mathbf{v}\|$. *Hint.* Start by simplifying $K\mathbf{v}$ as far as possible before calculating the length of this vector.

(12 pts) **Problem 3.** Fill-in the blank next to each of the following matrices with the appropriate notation to indicate the first step called for by the Gauß-Jordan algorithm as articulated in class. You do not need to perform the calculation but you must use correct notation to receive credit. (No partial credit. 2pts each)

$$\begin{bmatrix} 1 & -7 & 5 & 17 & 4 \\ 0 & 0 & 0 & 6 & 10 \\ 0 & 0 & -101 & 5 & 9 \\ 0 & 0 & 13 & 2 & 5 \\ 0 & 0 & 1 & 0 & 5 \end{bmatrix} \underline{\hspace{10em}}$$

$$\begin{bmatrix} 1 & 0 & 3 & 7 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \underline{\hspace{10em}}$$

$$\begin{bmatrix} 1 & 0 & -3 & 7 & 13 \\ 0 & 1 & 9 & 6 & 4 \\ 0 & 0 & 0 & 17 & 6 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix} \underline{\hspace{10em}}$$

$$\begin{bmatrix} 0 & 3 & 7 & 19 & 4 \\ 0 & 1 & 7 & 5 & 3 \\ 0 & 0 & 0 & 4 & 9 \\ 0 & -8 & 5 & 4 & 2 \end{bmatrix} \underline{\hspace{10em}}$$

$$\begin{bmatrix} 156 & 361 & 373 \\ 691 & 383 & 172 \\ 443 & 681 & 541 \\ 1 & 866 & 776 \\ 229 & 944 & 892 \end{bmatrix} \underline{\hspace{10em}}$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \underline{\hspace{10em}}$$

Problem 4. The following system of linear equations is consistent and in row echelon form.

$$\begin{array}{rcccccc} -2x_1 & + & 6x_2 & + & 3x_3 & - & 4x_4 & + & 5x_5 & = & -35 \\ & & & & 4x_3 & + & 8x_4 & - & 4x_5 & = & 4 \\ & & & & & & 6x_4 & + & 18x_5 & = & 24 \end{array}$$

Let A be the coefficient matrix of this system.

(2 pts) (a) Which variables in this system is *dependent*? Select all that apply (no partial credit).

- x_1 x_2 x_3 x_4 x_5

(6 pts) (b) Which of the following statements is true? Select all that apply (1.5pts each).

- A is full row rank A is full column rank A is rank deficient $A^T A$ is invertible

(10 pts) (c) Use back-substitution to express the general solution to this system as $\mathbf{x} = \mathbf{x}_p + c_1 \cdot \mathbf{x}_1 + c_2 \cdot \mathbf{x}_2$. Clearly explain your reasoning to receive credit. Fill in the blank vectors at the bottom of this page to make your answer clear.

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_p \\ \phantom{\mathbf{x}_p} \\ \phantom{\mathbf{x}_p} \\ \phantom{\mathbf{x}_p} \\ \phantom{\mathbf{x}_p} \end{bmatrix} + c_1 \cdot \begin{bmatrix} \mathbf{x}_1 \\ \phantom{\mathbf{x}_1} \\ \phantom{\mathbf{x}_1} \\ \phantom{\mathbf{x}_1} \\ \phantom{\mathbf{x}_1} \end{bmatrix} + c_2 \cdot \begin{bmatrix} \mathbf{x}_2 \\ \phantom{\mathbf{x}_2} \\ \phantom{\mathbf{x}_2} \\ \phantom{\mathbf{x}_2} \\ \phantom{\mathbf{x}_2} \end{bmatrix}$$

