DUKE UNIVERSITY

Матн 218D-2

MATRICES AND VECTORS

Exam III

Name:

Unique ID:

I have adhered to the Duke Community Standard in completing this exam. Signature:

April 18, 2025

- There are 100 points and 5 problems on this 50-minute exam.
- Unless otherwise stated, your answers must be supported by clear and coherent work to receive credit.
- The back of each page of this exam is left blank and may be used for scratch work.
- Scratch work will not be graded unless it is clearly labeled and requested in the body of the original problem.



Problem 1. Suppose that A = QR where A is 5×4 with rank(A) = 2. Let $P = QQ^{\intercal}$ and let d be the degree of the characteristic polynomial of P.

(4 pts) (a) Q is _____ × ____ and R is _____ × ____

(5 pts) (b) $d = \underline{\qquad}$ and the coefficient of t^{d-1} in $\chi_P(t)$ is _____

(4 pts) (c) $\operatorname{rank}(PA) =$ _____

Problem 2. Let $\boldsymbol{v} \in \mathbb{R}^2$ and let A be the matrix with eigenspaces $\mathcal{E}_A(-2) = \operatorname{Span}\left\{ \begin{bmatrix} 1\\1 \end{bmatrix} \right\}$ and $\mathcal{E}_A(1) = \operatorname{Span}\{\boldsymbol{v}\}$.

(4 pts) (a) $\begin{bmatrix} & A \\ & \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \\ & \\ & \end{bmatrix}$

(4 pts) (b) Suppose $x \neq 0$. Only one of the following choices for the vector v makes the matrix A real-symmetric. Select this vector.

$$\bigcirc \mathbf{v} = \begin{bmatrix} x \\ x \end{bmatrix} \quad \bigcirc \mathbf{v} = \begin{bmatrix} x \\ -x \end{bmatrix} \quad \bigcirc \mathbf{v} = \begin{bmatrix} -x \\ -x \end{bmatrix} \quad \bigcirc \mathbf{v} = \begin{bmatrix} x \\ 0 \end{bmatrix} \quad \bigcirc \mathbf{v} = \begin{bmatrix} 0 \\ x \end{bmatrix}$$

(10 pts) (c) Calculate the matrix-vector product $\begin{bmatrix} & A \\ & \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} & & \\ & & \\ \end{bmatrix}$ assuming that $\boldsymbol{v} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$.

Problem 3. This 4×4 matrix A has exactly two eigenvalues. One of the eigenvalues of A is $\lambda_1 = 3$. The geometric and algebraic multiplicities of $\lambda_1 = 3$ satisfy

$$\operatorname{gm}_A(3) = \operatorname{am}_A(3) = 2$$

$$A = \begin{bmatrix} -3 & -41 & -4 & -6\\ 3 & 24 & 2 & 3\\ -12 & -86 & -5 & -12\\ -9 & -63 & -6 & -6 \end{bmatrix}$$

The other eigenvalue λ_2 is unknown. It is known that A is not diagonalizable.

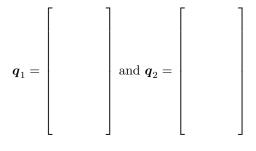
(6 pts) (a) $\operatorname{gm}_A(\lambda_2) = \underline{\qquad}$ and $\operatorname{am}_A(\lambda_2) = \underline{\qquad}$

(10 pts) (b) Calculate the values of λ_2 and det(A). Clearly explain your reasoning to receive credit and fill in the blanks below to make your answers clear.

The context of this problem allows for the calculation of these numbers with minimal arithmetic, so no partial credit for arithmetic errors will be awarded.

 $\lambda_2 = ___$ and det $(A) = __$

(10 pts) (c) There is a basis of $\mathcal{E}_A(3)$ of the form $\{\boldsymbol{v}_1, \boldsymbol{v}_2 = \begin{bmatrix} -2 & 0 & 3 & 0 \end{bmatrix}^{\mathsf{T}} \}$. Find a valid choice for \boldsymbol{v}_1 and then use your basis $\{\boldsymbol{v}_1, \boldsymbol{v}_2\}$ to find an *orthonormal* basis $\{\boldsymbol{q}_1, \boldsymbol{q}_2\}$ of $\mathcal{E}_A(3)$. Clearly explain your reasoning to receive credit and fill in the blank vectors below to make your answer clear.



(16 pts) **Problem 4.** Let *H* be the Hermitian matrix $H = \begin{bmatrix} 2 & -i \\ i & 2 \end{bmatrix}$. Calculate $2 \cdot \exp(H)$. Clearly explain your reasoning and fill in the blank matrix below to make you answer clear.

 $2 \cdot \exp(H) =$

Problem 5. Consider the singular value decomposition $A = U\Sigma V^{\intercal}$ where

$$A = \begin{bmatrix} -\frac{1}{42} & \frac{1}{6} & \frac{1}{21} & \frac{5}{21} \\ \frac{2}{7} & \frac{3}{14} & -\frac{3}{14} & \frac{1}{14} \\ -\frac{1}{42} & \frac{5}{21} & -\frac{1}{6} & -\frac{5}{42} \\ \frac{1}{42} & -\frac{1}{6} & -\frac{1}{21} & -\frac{5}{21} \\ -\frac{1}{3} & \frac{4}{21} & \frac{2}{21} & \frac{1}{121} \end{bmatrix} \quad U = \frac{1}{\sqrt{7}} \begin{bmatrix} 1 & 1 & -1 \\ -1 & 2 & 0 \\ 0 & 1 & 2 \\ -1 & -1 & 1 \\ 2 & 0 & 1 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1/2 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \quad V = \frac{1}{\sqrt{7}} \begin{bmatrix} -2 & 1 & -1 \\ 1 & 2 & 1 \\ 1 & -1 & -1 \\ 1 & 1 & -2 \end{bmatrix}$$

Note that A is 5×4 (which means that $A^{\intercal}A$ is 4×4).

(9 pts) (a) rank(A) = _____, trace(U^TU) = _____, and det(V^TV) = _____

(4 pts) (b) Only one of the following statements accurately describes the definiteness of $A^{\intercal}A$. Select this statement.

- $\bigcirc A^{\intercal}A$ is indefinite $\bigcirc A^{\intercal}A$ is positive semidefinite and positive definite
- \bigcirc the concept of definiteness does not apply to $A^{\intercal}A \bigcirc A^{\intercal}A$ is positive semidefinite but not positive definite
- $\bigcirc A^{\mathsf{T}}A$ is positive definite but not positive semidefinite

(4 pts) (c) Only one of the following statements accurately describes the eigenspaces of $A^{\intercal}A$. Select this statement.

- $\bigcirc\ A^\intercal A$ has one two-dimensional eigenspace and two one-dimensional eigenspaces
- $\bigcirc A^{\intercal}A$ has four one-dimensional eigenspaces $\bigcirc A^{\intercal}A$ has three one-dimensional eigenspaces
- $\bigcirc A^{\intercal}A$ has one two-dimensional eigenspace and one one-dimensional eigenspace
- $\bigcirc A^{\intercal}A$ has one three-dimensional eigenspace
- (10 pts) (d) Let \hat{x} be any solution to the least squares problem associated to Ax = b where $b = \begin{bmatrix} 0 & \sqrt{7} & 0 & 0 & 0 \end{bmatrix}^{\mathsf{T}}$. Calculate $V^* \hat{x}$. Clearly explain your reasoning to receive credit. *Hint.* Start by clearly articulating what system \hat{x} solves and explain the relevance of SVD to this system.